CANPro Technical Manual
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CAN Commands

COMMANDS

General

List of Commands

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- Groups of Identifiers
- CAN Identifier List
- CAN Register

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Description of Commands

- AD Abort Done
- AS Abort Start
- BA Break All Move
- BH Break Horizontal Move
- BT Break Tilt Move
- BV Break Vertical Move
- CH Cancel Horizontal Position
- CM Cancel Mode
- CS Cancel Scan
- CT Cancel Tilt Position
- CV Cancel Vertical Position
- E# Error
- FB Flash Block Number
- FC Flash Clear
- FD Flash Load Done
- FR Flash Read
- FS Flash Load Start
- FV Flash Verify
- GH Go Horizontal Move
- GT Go Tilt Move
- GV Go Vertical Move
- HD Halt Done
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- IR Init Request
- IS Init Start
- KA Key API Lamp
- KD Keys Disable
- KE Keys Enable
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- KN Keys Normal
- LC Loaded Detector Comb (P20 only)
- LD Loaded Detector Collimator (P20 only)
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- LR Loaded Rotation
- LS Loaded Scan
- LT Loaded Tube Collimator
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- PO Position Option (P20 only)
- PT Position Tilt
- PV Position Vertical
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- QD Quality Service done
- QS Quality Service Start
- RD Reset Done
- RS Reset Start
- RW Reset Working
- SE Start Execute
- SF Start Footswitch
- SJ Start Jump
- SL Start Load
- U# Table Query
- V# Table Verified
- XA Anode Executed
- XF Filament Executed
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CAN Commands

TABLES

TABLES

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CAN Commands

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CAN Tables

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  - T10 : state GPC
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  - T90 : state DLP
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  - T06 : MCU Timeout Table
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  - Collision Parameters Drawing
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- General and List

T0A - T0F : MCU Application Tables

- T0A : WCS parameters
- T0B : Configuration
- T0C : Parameters for gantry climate control

T1A - T1F : GPC Application Tables

- T1A : GPC Limit Values
- T1B : GPC Slice Difference
- T1C : GPC positioning speed and fine positioning

T2A - T2F : RTC Application Tables

- T2A : RTC Machine Parameters
- T2B : RTC AP Timing

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- T3C : PTH Motion Controller Parameters
- T3D : PTH Move Parameters

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- T4C : PTV Frequency Converter Table

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- T5C : XRS Self Test Table
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- T9A : DLP Init Table
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